RIEGL VZ-600i

Scanner Performance (continued)

Orientation Sensors	integrated 3-axis accelerometer, 3-axis gyroscope, 3-axis magnetometer (compass), barometer		
GNSS Receiver	integrated L1 GNSS receiver, optional external RIEGL GNSS RTK receiver (L1/L2)		
Waveform Data Output (optional hardware configuration)	providing digitized echo signal information for specific target echoes hardware option to be selected in the course of the ordering process		
Data Storage	integrated SSD 2 TByte, removable CF-Express card 512 GByte (1 TByte optionally available), automatic sync while scanning		
Cloud Storage	Amazon S3, FTP-Server, Microsoft Azure		
on-board Registration	automatic scan data registration as background process while scanning		

Scanner Control

via Laser Scanner	7 inch touch screen, 1280 pixel x 800 pixel	
via Mobile Device(WiFi)	"RIEGL VZi-Series"-App, available for iOS and Android	
via ROS	ROS (Robot Operation System) driver available	

Camera

Internal Camera	3 x 12 MPix CMOS color cameras, FOV 115° x 40° (v x h)
Anonymization of Image Data 1)	resolution of panoramic image 199 MPixel
	optional on-board face and license plate detection and automatic blurring in real time before image storage
External Camera (optional)	detachable SONY ILX-LR1 & SONY SEL14F18GM lens resolution of panoramic image 137 MPixel
Panorama Camera (optional)	detachable RICOH Theta Z1 resolution of panoramic image 23 MPixel

1) To comply with the requirements of the European General Data Protection Regulation (GDPR), among others

General Technical Data

Internal Power Supply	2 x Li-lon hot-swap rechargeable batteries			
	99 Wh ²⁾ , up to 90 minutes operating time, each <0.5 kg/1.1 lbs each			
External Power Supply	input voltage 11 - 34 V DC			
Power Consumption	Typ. 72W, max. 85 W (without external devices)			
Main Dimensions	173 mm x 305 mm x 184 mm			
(width x height x depth)				
Weight	Scanner without battery <6 kg / 13 lbs			
Humidity	max. 80 % non condensing @ +31 °C			
Protection Class	IP64, dust-tight and splash-proof			
Temperature Range				
Storage / Operation	-10 °C up to +50 °C / 0 °C up to +40 °C: standard operation			
Low Temperature Operation 3)	-20 °C: continuous scanning operation if instrument is powered on while internal			
·	temperature is at or above 0 °C and still air			
	-40 °C: scanning operation for about 20 minutes if instrument is powered on while			
	internal temperature is at or above 15 °C and still air			

2) The capacity of the battery according to the cell manufacturer's specifications, the capacity available in the application is lower 3) Insulating the scanner with appropriate material will enable operation at even lower temperatures.



RIEGL Laser Measurement Systems GmbH, Headquarters RIEGL USA Inc., Headquarters North America

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Terrestrial Laser Scanning



RIEGL VZ-600i

Exceeding your expectations



RIEGL VZ-600i

RIEGL's latest generation of professional Terrestrial Laser Scanners stands for extreme versatility, high productivity, ultimate performance, and additional mobility – providing an excellent return on investment.



High Productivity

- 60 scan positions per hour (with image acquisition)
- One-Touch button operation
- RIEGL VZ-i Project Map App for scan project monitoring
- simultaneous scan and image data acquisition
- Real-Time on-board automatic registration
- One-Touch Processing Wizard in RISCAN PRO for automatic production of detailed PDF-report



Extreme Versatility

- for various applications
- indoor and outdoor 3D mapping
- internal cameras and GNSS receiver
- lightweight (approx. 6 kg / 13 lbs)
- prepared for user-specific Python apps



Ultimate Performance

- broad range capability (0.5 m up to 1000 m)
- 5 sec scan time for low resolution overview scans
- 30 sec scan time for 6 mm resolution @ 10 m distance
- pulse repetition rate up to 2.2 MHz
- 3D position accuracy up to 3 mm @ 50 m
- scan speed up to 420 lines/sec
- high speed data download of up to 500 MB/sec



Additional Mobility

- prepared for robotic operation (ROS driver available)
- option for mobile mapping
- can be used with the RIEGL VMR Robotic Rail Scanning System
- flexible mounting platforms

Ultimate Performance – Technical Data

Laser Product Classification

Class 1 Laser Product according to IEC 60825-1:2014

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for conformance with IEC 60825-1 Ed.3., as described in Laser Notice No. 56, dated May 8, 2019.



Range Measurement Performance

Measuring Principle / Mode of Operation	time of flight measurement, echo signal digitization, online waveform processing			
Laser Pulse Repetition Rate (PRR) – (peak) 1)	2200 kHz	1200 kHz	600 kHz	140 kHz
Max. Measuring Range $^{2)}$ natural targets $\rho \geq 90$ % natural targets $\rho \geq 20$ %	220 m 100 m	320 m 150 m	420 m 200 m	1000 m 450 m
Minimum Range 3)	0.5 m	0.5 m	0.5 m	1 m
Max. Number of Targets per Pulse 4)	5	10	15	15
Precision 5) 6)	3 mm	3 mm	3 mm	3 mm
Ranging Accuracy 6) 7)	5 mm			
3D Position Accuracy 8)	3 mm @ 50 m, 5 mm @ 100 m			
Laser Wavelength	near infrared, invisible			
Laser Beam Divergence	0.35 mrad ⁹⁾ / 0.25 mrad ¹⁰⁾			

- 1) Rounded values.
- Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.
- 3) Minimum range specified for vertical zenith angles from 25 deg to 130 deg, resp. 105° vertical field of
- 4) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achieveable
- range is reduced. 5) Precision, also called reproducibility or repeatability, is the degree to which repeated measurements
- show the same result.
 1-sigma value @ 100 m range under RIEGL test
- 7) Accuracy is the degree of conformity of a measured quantity to its actual (true) value
- 8) 1-sigma value, based on target modelling, under RIEGL test conditions.
 9) Measured at the 1/e2 points. 0.35 mrad corre-
- sponds to an increase of 35 mm of beam diamete per 100 m distance.
- Measured at the 1/e points. 0.25 mrad corresponds to an increase of 25 mm of beam diameter per 100 m distance

Scanner Performance

Vertical (Line) Scan	Horizontal (Frame) Scan			
total 105° (+65° / -40°)	max. 360°			
rotating multi-facet mirror	rotating head			
4 lines/sec to 420 lines/sec	0°/sec to 360°/sec 11)			
scan time less than 30 seconds for "Panorama_6mm" (approx. 30 Mio measurements) 6 mm resolution @ 10 m distance, up to 60 scan positions per hour (including scan and image acquisition with real-time on-board registration)				
$0.0007^{\circ} \le \Delta \vartheta \le 0.54^{\circ}$ between consecutive laser shots	$0.0015^{\circ} \le \Delta \phi \le 0.86^{\circ}$ between consecutive scan lines			
0.0028° (10 arcsec) 0.0028° (10 arcsec)				
better 0.0007° (2.5 arcsec)	better 0.0005° (1.8 arcsec)			
	total 105° (+65° / -40°) rotating multi-facet mirror 4 lines/sec to 420 lines/sec scan time less than 30 seconds for "Pane (approx. 30 Mio measurements) 6 mm resolution @ 10 m distance, up to 60 scan positions per hour (including scan and image acquisition with $0.0007^{\circ} \le \Delta 9 \le 0.54^{\circ}$ between consecutive laser shots 0.0028° (10 arcsec)			

¹¹⁾ Frame scan can be disabled, providing 2D scanner operation. 12) Selectable.

Technical Data to be continued at page 8



^{13) 1-}sigma value, based on target modeling, under RIEGL test conditions